

# Feature Studies for PV Fault Classification Using Nonlinear Principal Component Analysis

**SenSIP Algorithms and Devices IRES**

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## ABSTRACT

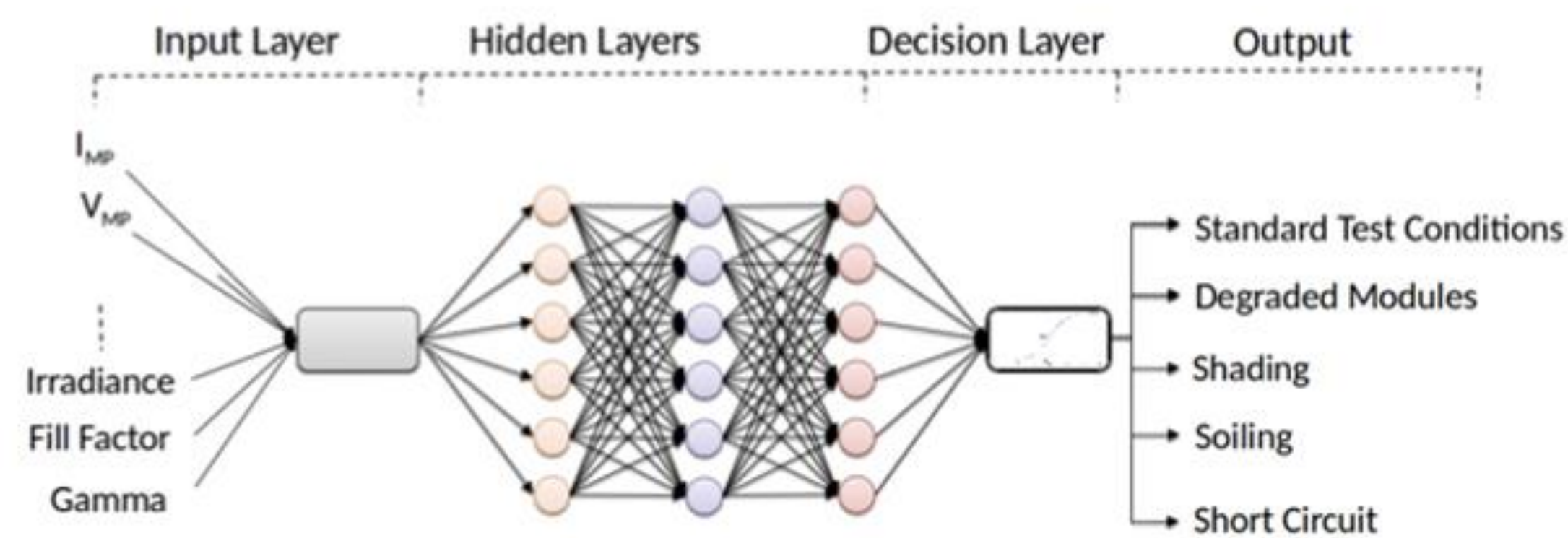
- Neural networks can be used to classify solar faults
- Nonlinear principal component analysis can show redundancies in input features.
- Reducing the dimensions of the input features can simplify the neural network
- The simplified network maintains accuracy.

## MOTIVATION

- The current model has difficulty distinguishing between STC and shaded faults.
- Passing the data through a kernel function or encoder NN may be able to separate these classes.
- Not all features may be necessary for the network.
- PCA can inform us to which features are most important.
- Nonlinear PCA methods may be more effective if the input features are nonlinearly dependent.

## PROBLEM STATEMENT

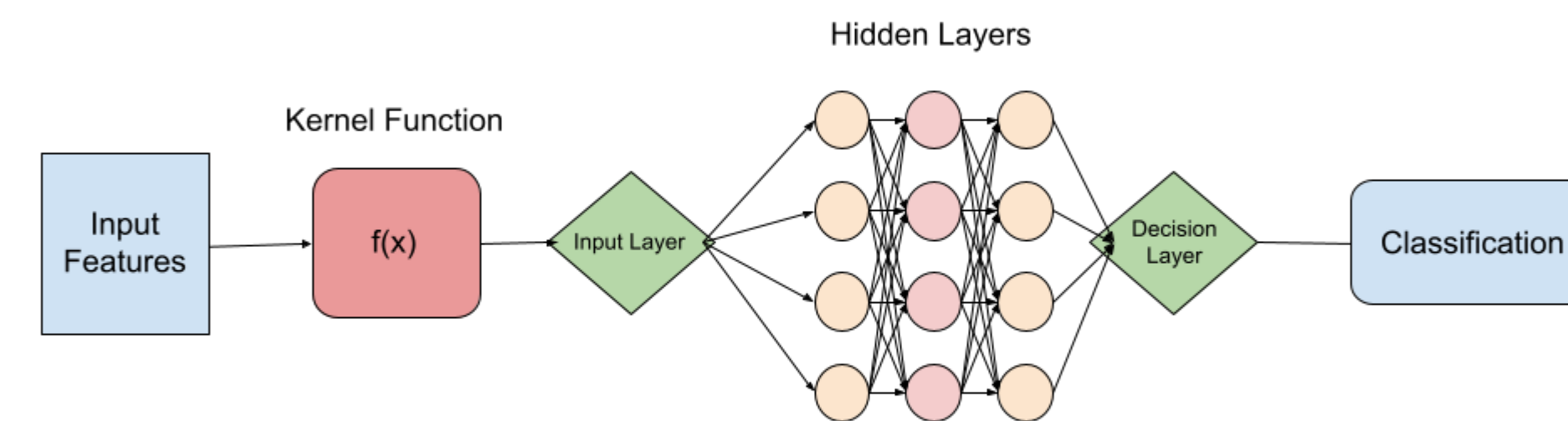
- The importance of PV features in classifying faults is unknown, and the current NN model is unable to distinguish between STC and shaded faults with the current dataset.



## EXPERIMENTAL METHODS

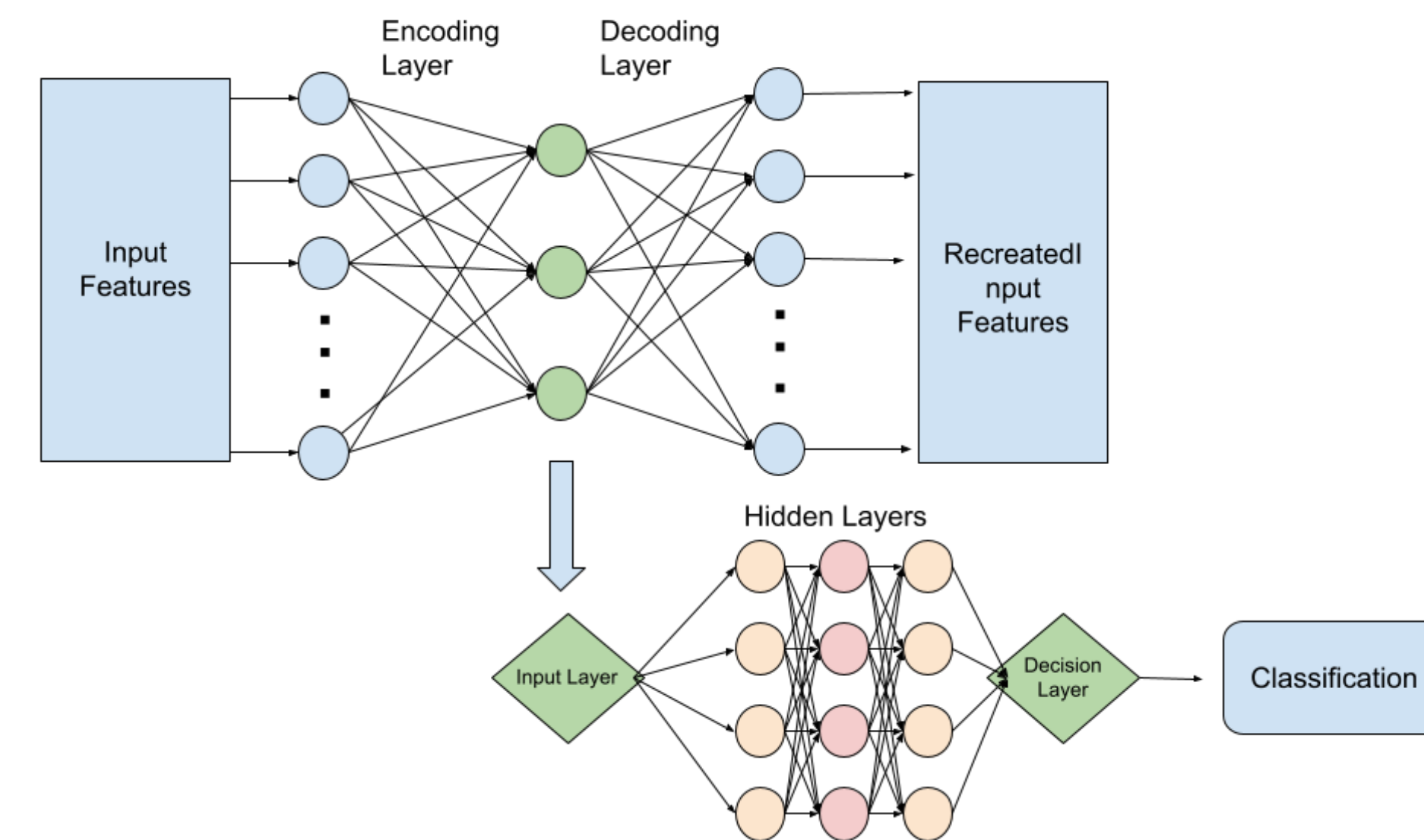
### Kernel PCA

- Pass the feature data through multiple kernel functions.
- Select different numbers of input features and pass the modified data into a NN for fault classification.



### Autoencoder

- Train a neural network that encodes the data to a specified number of dimension then decodes it.
- Take the output of the encoded layer and pass it into a fault classification NN



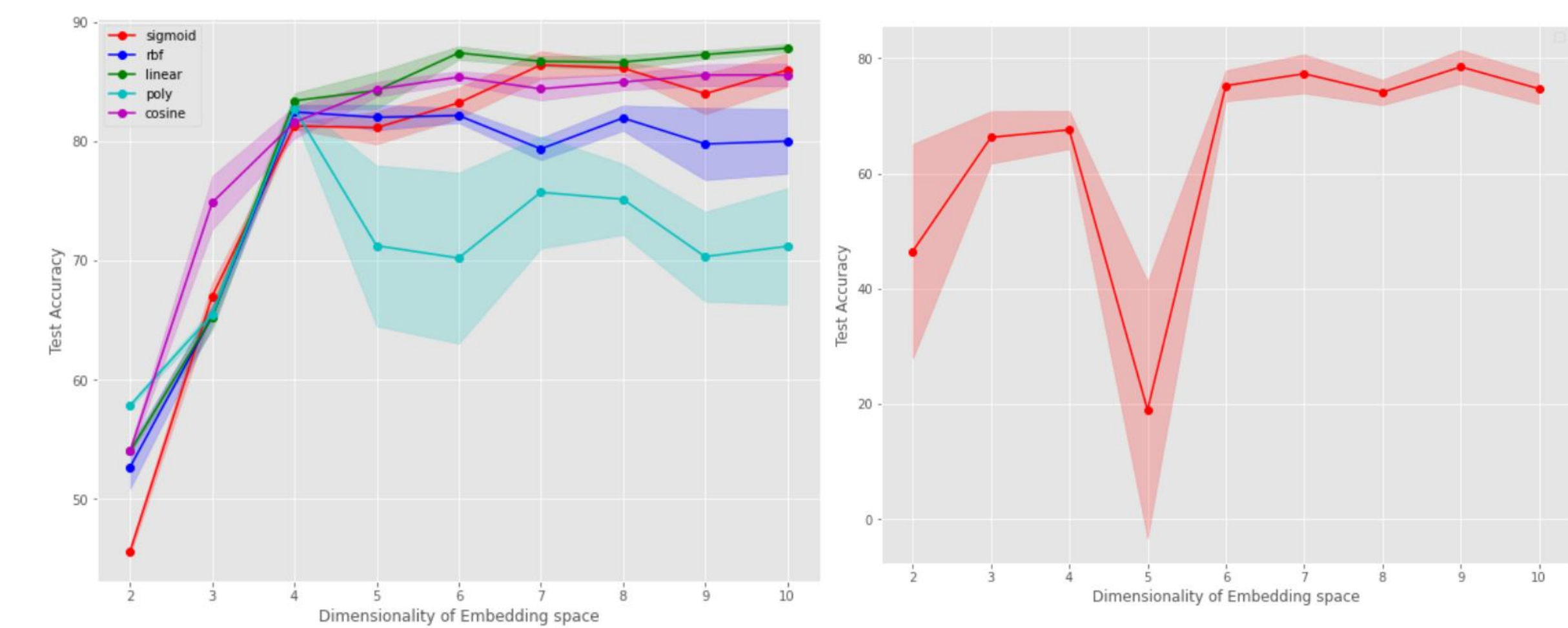
## PRELIMINARY RESULTS

### Kernel PCA

- Linear Kernel Function is the most accurate
- Classification accuracy levels for 5+ features

### Autoencoder

- The autoencoder was less accurate overall with <80% accuracy



## REFERENCES

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