

Image Subsampling Strategies for Energy-Efficient Computer Vision

SenSIP Algorithms and Devices REU

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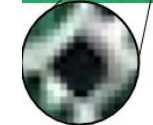
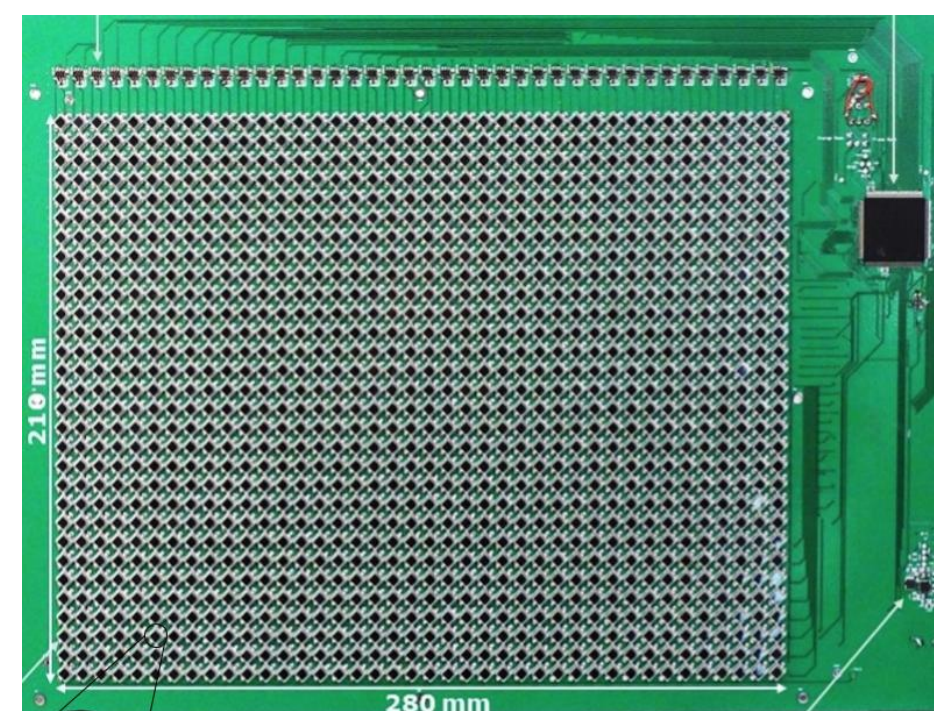


1. ABSTRACT

- Trend in industry: enable embedded and mobile platforms to become more energy-efficient
- To be more energy-efficient, machines performing a computer vision task utilize image subsampling
- We propose using a heuristic algorithm to determine the most energy-efficient subsampling for a given image.

2. MOTIVATION

- Efficient bandwidth usage
 - Improved bit rate if transmission is required
 - Reduce memory storage
-
- Specific application: self-powered cameras
 - An array of photodiodes that can capture light intensity either to produce a pixel of an image or to harvest energy
 - Objective: allow the self-powered camera to utilize more photodiodes for energy harvesting



Photodiode

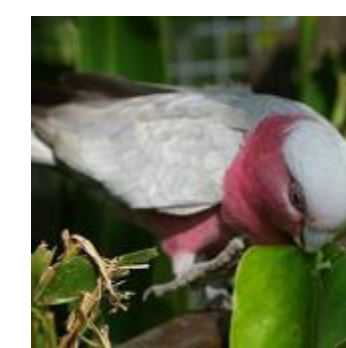
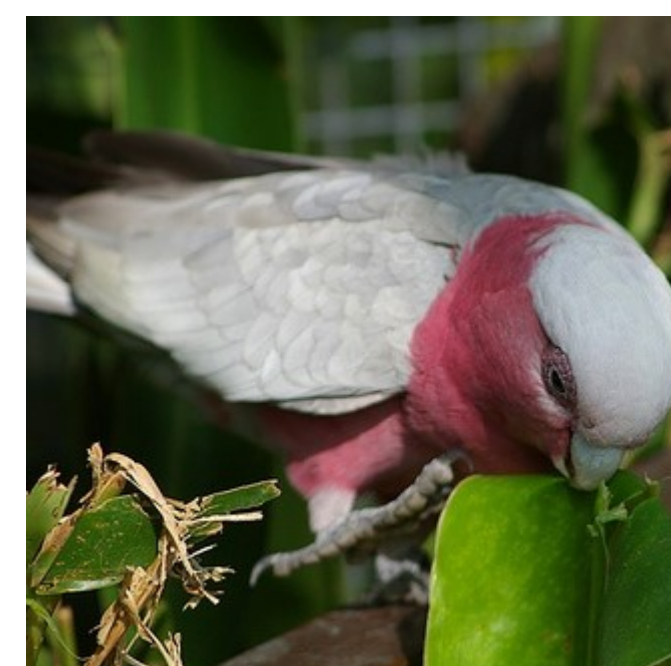
Figure adapted from [1]

3. PROBLEM STATEMENT

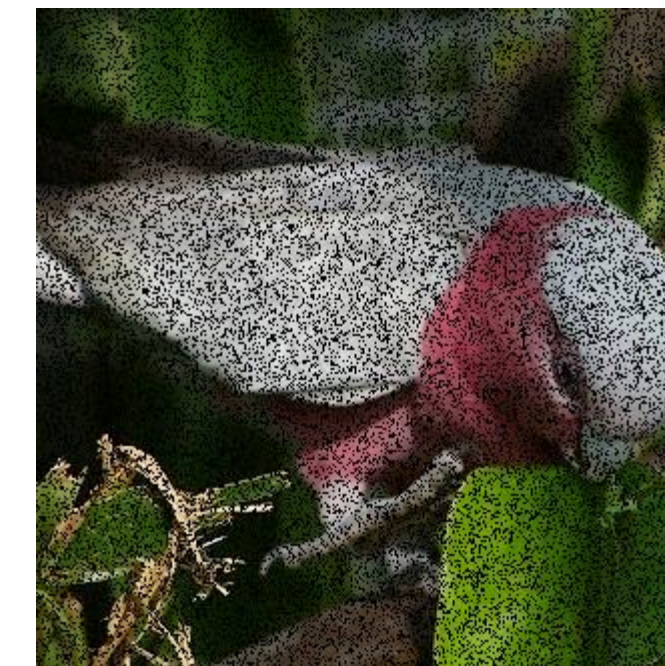
- Given an N-by-M image, how many pixels can be removed from said image such that a computer vision task can still be performed accurately?

4. METHODS OF IMAGE SUBSAMPLING

- Many methods of image subsampling have been developed already (e.g. downsampling the dimension of an image)
- We propose a simple method of image subsampling: removing pixels from an image



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Original Image

Random Pixelation

- Two image subsampling patterns:
 - Removing different numbers of pixels randomly
 - Removing pixels in a checkerboard pattern, varying the size of the alternating squares

6. BENCHMARK FOR COMPUTER VISION ACCURACY

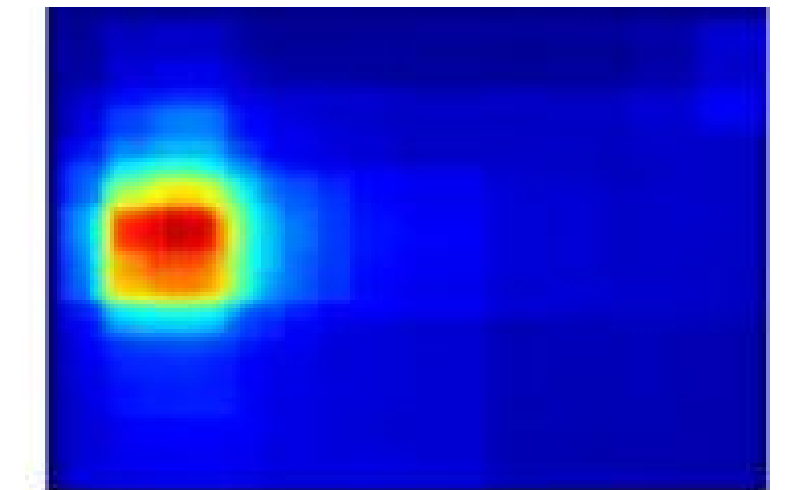
- Three benchmarks for computer vision:
 - Object Detection
 - Classification
 - Semantic Segmentation
- Determine the relationship between the benchmark's measure of error and MSE



Figure from [3]

5. MEASURING COMPUTER VISION ACCURACY

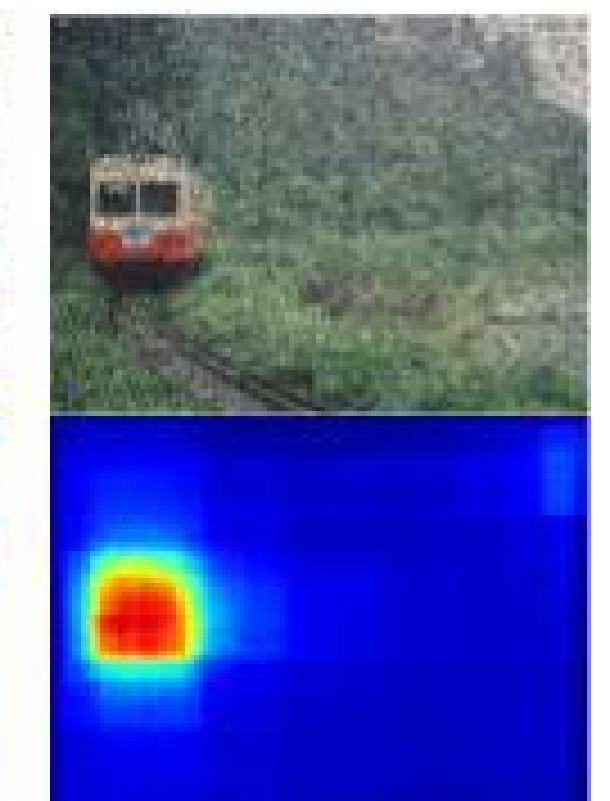
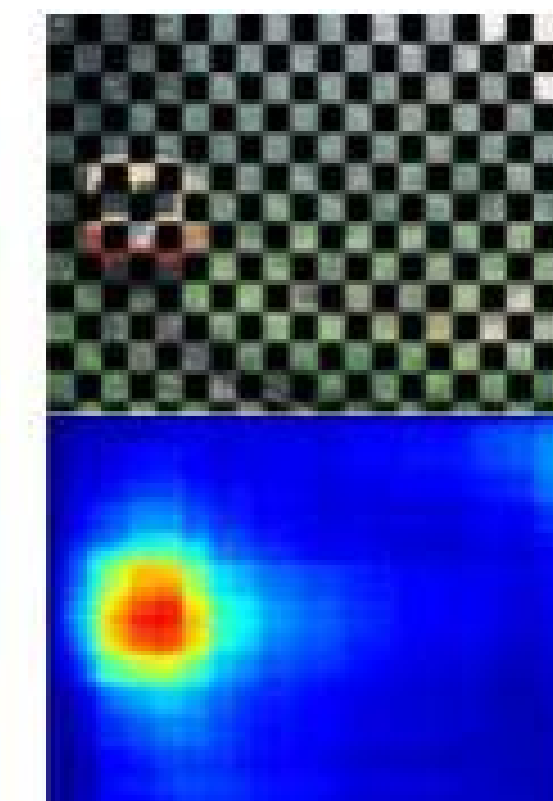
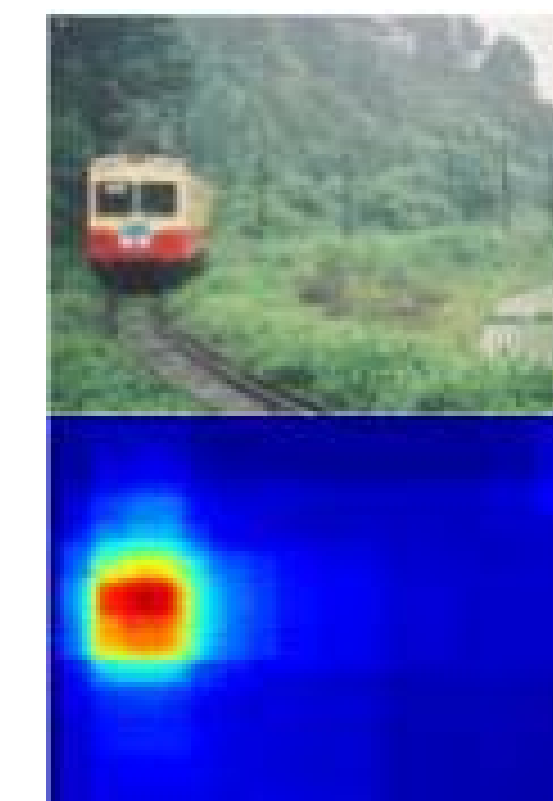
- Produce an importance map of an image that detects the likelihood of an object at a given region of the image



Original Image

Importance Map

- Produce an importance map of the image after subsampling
- Calculate the Mean Square Error (MSE) between the importance map of the ground truth image and the subsampled image



• Ground Truth Image

• Checkerboard Mask

• Random Pixelation

• MSE: 0.0223

• MSE: 0.0067

- Analyze relationship between subsampling pattern and MSE

7. REFERENCES

- [1] S. K. Nayar et al., "Towards self-powered cameras," in *Computational Photography (ICCP)*, 2015. IEEE, 2015, pp. 1–10.
- [2] B. Alexe, T. Deselaers, and V. Ferrari, "What is an object?" in *CVPR, 2010 IEEE Conference on*. IEEE, 2010, pp. 73–80.
- [3] A. Vedaldi et al., "Matconvnet: Convolutional neural networks for matlab," in *Proc. of the 23rd ACM international conf. on Multimedia*. ACM, 2015, pp. 689–692.

8. ACKNOWLEDGEMENT

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