

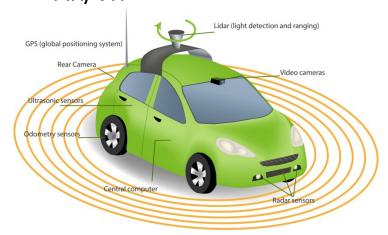
RET PROJECT: DEEP LEARNING-BASED MONOCULAR DEPTH ESTIMATION

Ebubekir Sen¹, David Ramirez², Andreas Spanias²
[1] Sonoran Science Academy Tucson [2] SenSIP Center, School of ECEE at ASU



Problem:

 3D surrounding is essential in robotics, autonomous vehicles, AR/VR



- Multiple sensors :LIDAR, RADAR, camera
- Cost of sensors

Current Studies:

- Deep Learning based depth estimation uses only a camera
- Monocular cameras-Dynamic
- Multi-view cameras -Static
- No need for LIDAR depth values
- Effective methods are limited within a dataset

Seq=07, KF=395



Our Study:

- Combining strengths of previous studies
- State of the art results
- Large scale reconstruction
- Effective in other datasets:
 KITTI, Oxford Robot-Car
- Camera as lead sensor
 Depth Map

