



# Baby Boot: Devising a Multimodal Sensor for Enhanced Infant Monitoring

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REU Site sponsored in part  
by NSF I/UCRC Award 1659871

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<http://sensip.asu.edu>

# Presentation Agenda

1. ASU Pre-Training
2. Problem Statement and Challenges
3. Proposed Solution
4. Structure of Circuits & Algorithms
5. Research Contribution
6. Results
7. Research Conclusion
8. Next Steps
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# REU Pre-Training

## Hands On Technical Training

- MATLAB and Python refresher
  - Activities ranged from noise reduction to digit recognition
- Machine Learning boot camp by Dr. Kristen Jaskie on Colab
  - Clustering + K-means
  - Regression + Prediction
  - Classification + Neural Networks
- Embedded Hardware for ML by Micheal Stanley
  - Learned about factors to consider when a sensor hardware platform

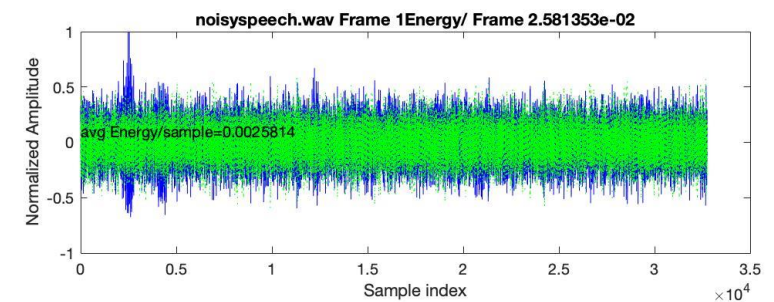
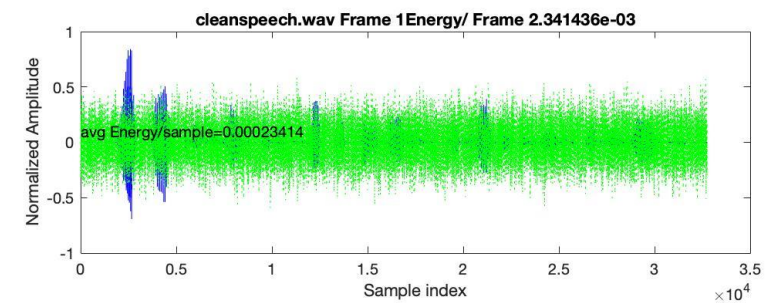
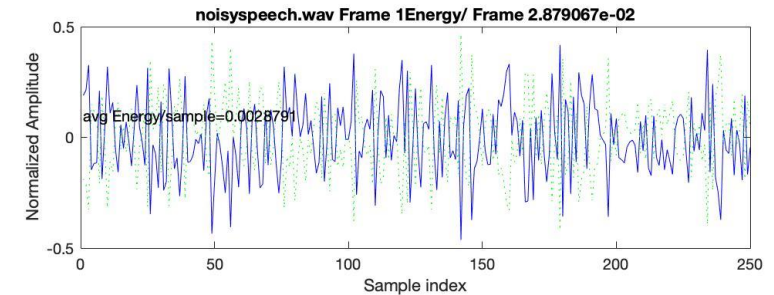
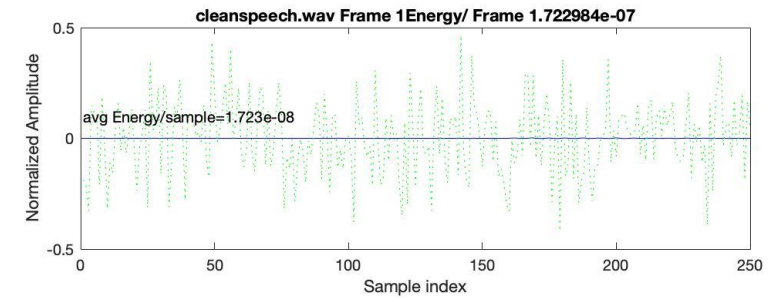


Fig: Noise reduction MATLAB plots

# Problem Statement

## Background

- Unless in immediate medical danger, newborns one hour postpartum are generally placed on the mother's chest to promote critical social bonding.
- During this period, babies are not intensely monitored.
- Without sensors during one-on-one contact, any concerning internal issues developed in the baby as a result of the trauma of birth is allowed to fester. Delayed medical intervention of such symptoms has been linked to hypoxia and cerebral palsy.

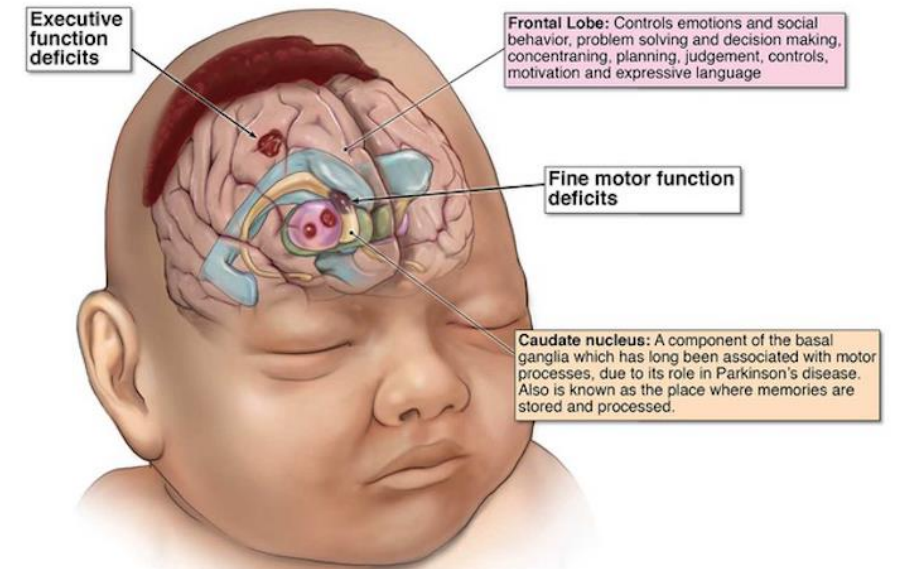
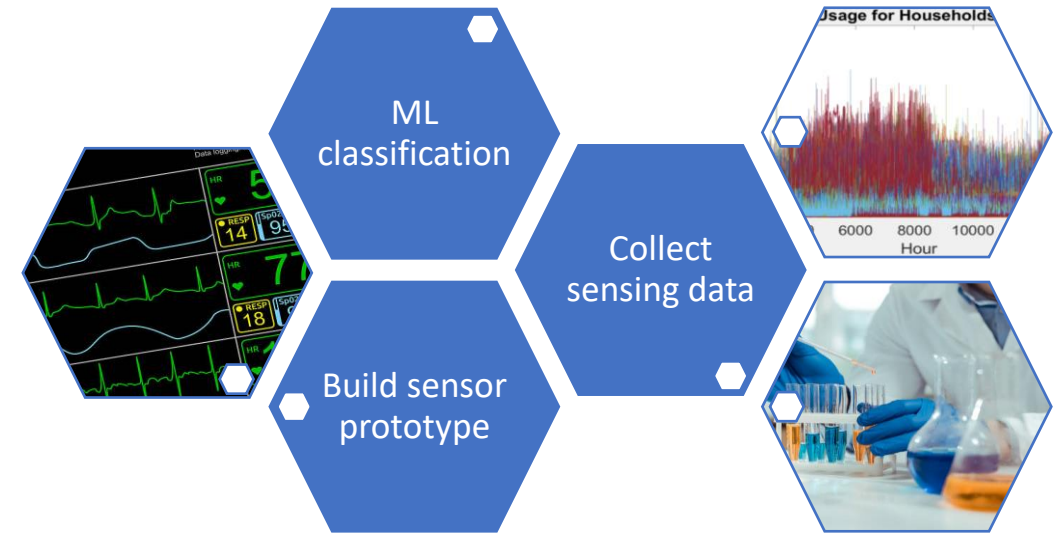


Fig: (Top) Example of crucial skin-skin contact between infant and mother; (Bottom) Hypoxia as it develops in babies

# Proposed Solution

## Research Goal

- “Baby Boot,” originally pitched by KLS OB-GYNs, is a flexible electronic multimodal sensor that can be easily worn by babies as a “boot”.
- The device will detect and transmit data about crucial analytes: pH, O<sub>2</sub>, CO<sub>2</sub>, and glucose levels.
- A machine learning classification algorithm will be used to analyze data and alert doctors of potential health risks.



*Fig: (Top) Chart that displays the three main components of the project: Data collection, prototyping, and ML Classification; (Bottom) Oxlet commercial (non-medical) baby boot as an example of the proposed sensor design*



# Structure of Circuits and Algorithms

## Research Tools

- Designed and printed glucose sensor for laboratory testing

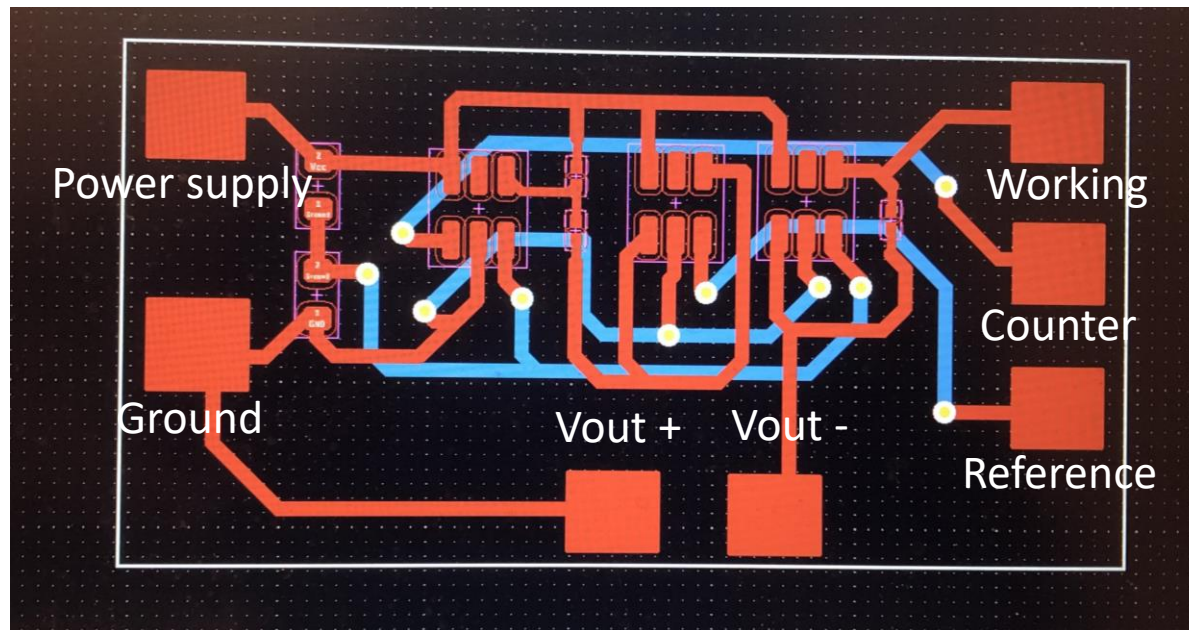


Fig: Circuit schematic of a three-electrode system glucose sensor used in testing

- Logistic regression to classify
  - pH sensor data
  - Glucose sensor data
  - Healthy and unhealthy babies using pH, O<sub>2</sub> and base excess

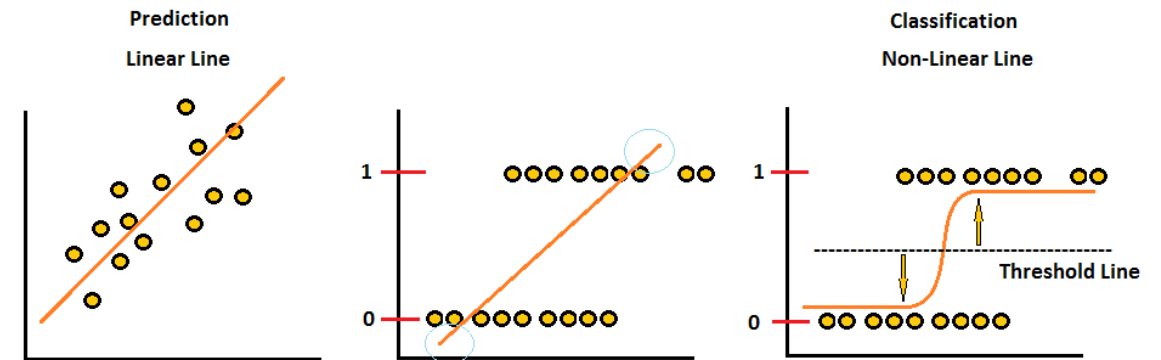


Fig: Diagram explaining classification using logistic regression

# Research Contribution

## Research Focus Areas

- Sensor selection
  - To devise a prototype for testing quickly – through literature/commercial product review was conducted
- Machine learning
  - ML algorithms were explored to test in characterizing benchtop data
  - Determine the importance of analytes in sensor development
    - What analyte is not as crucial for neonatal monitoring?

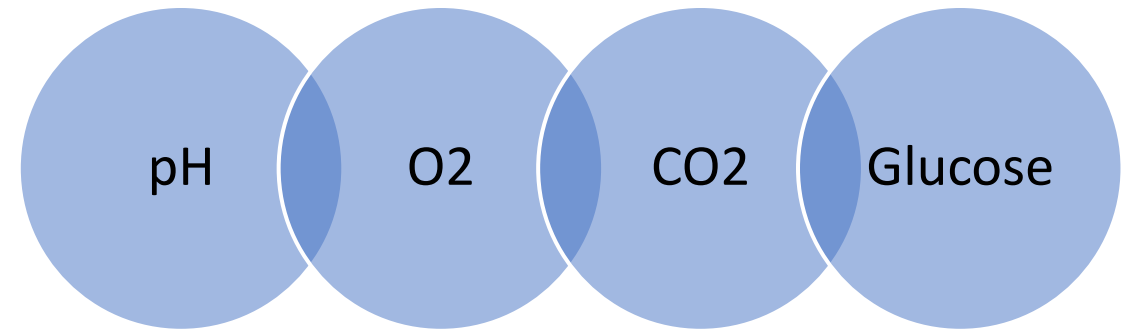


Fig: List of analytes that the sensor will observe

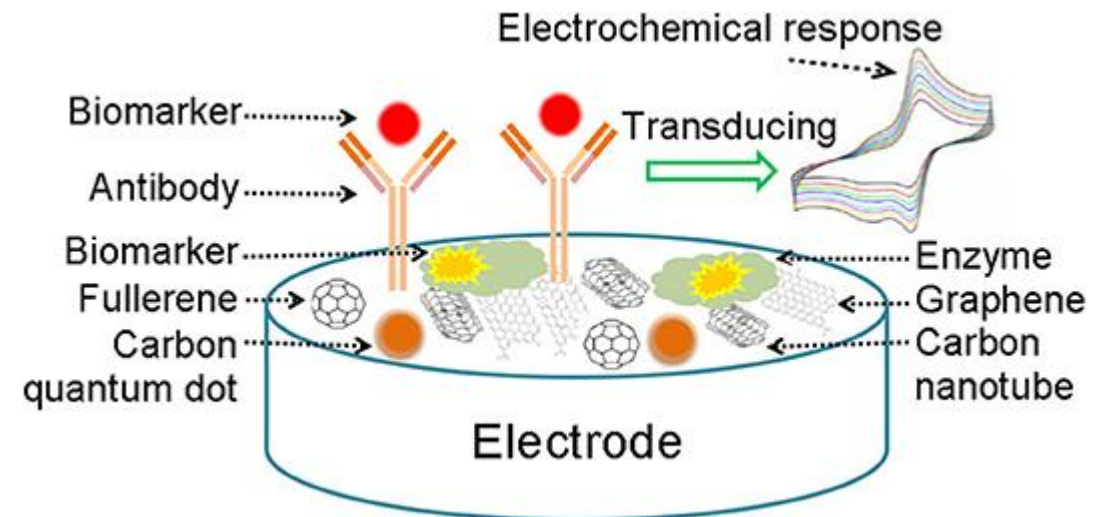


Fig: Diagram illustrates the various considerations in sensor development – from electrode system, modality (invasive/noninvasive), to analyte-detecting enzyme

# Results - Sensor Development

- CO<sub>2</sub>: commercially unavailable – sparked ML research to determine whether important
- pH: currently being developed in BEST Lab, benchtop experiments to refine accuracy
- Glucose: progression from taking apart/hacking Freestyle glucose sensor, developing circuit
- O<sub>2</sub> – commercially available, easiest to implement
- Set-up Nordic BLE



Fig: Disassembled FreeStyle sensor

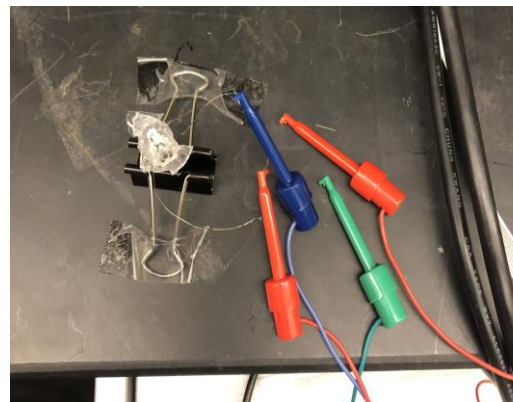


Fig: pH sensor experimental set-up

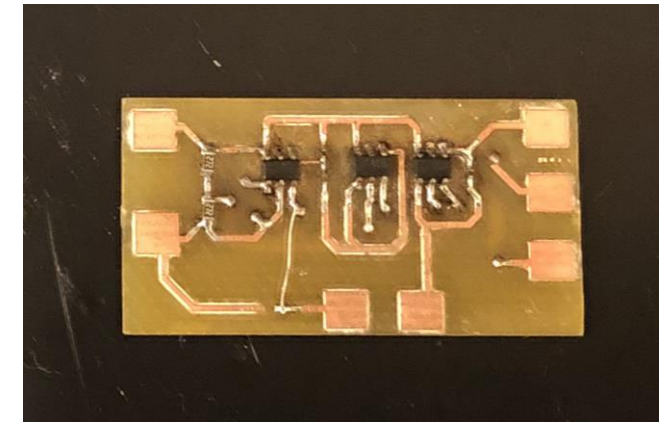


Fig: Printed glucose sensor PCB

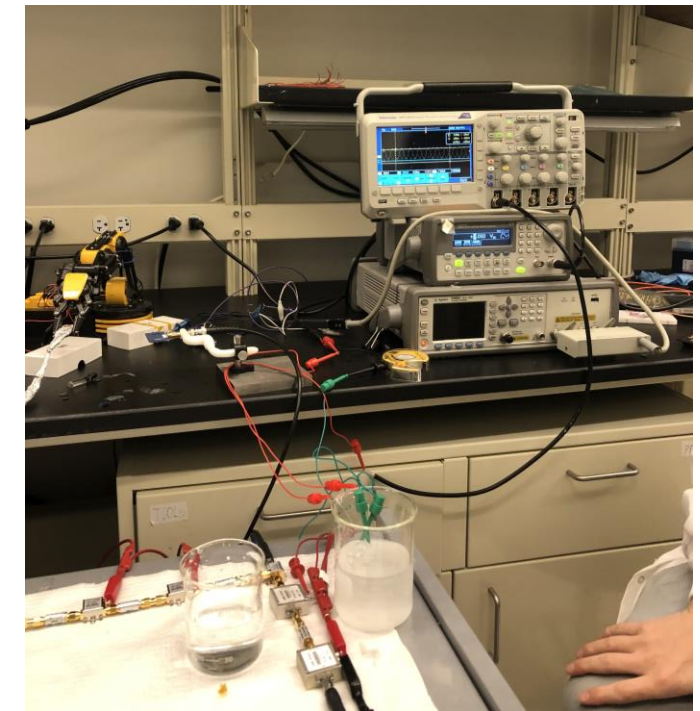


Fig: Glucose experiments for data collection



# Results

- Collected pH data and glucose data to train logistic regression ML algorithms
- Utilized KLS dataset to determine healthy vs. unhealthy babies from pH, O<sub>2</sub>, CO<sub>2</sub>, and base excess
- ML algorithm to rank the importance of analytes – to verify accuracy of prototype without CO<sub>2</sub>



Fig : Keeping Labor Safe (KLS) investors/medical collaborators of the Baby Boot project

Metric	Value
Accuracy	0.98

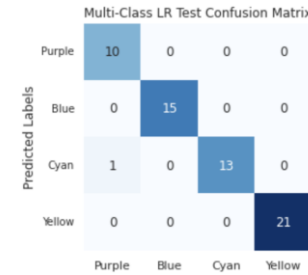


Fig: pH classification confusion matrix

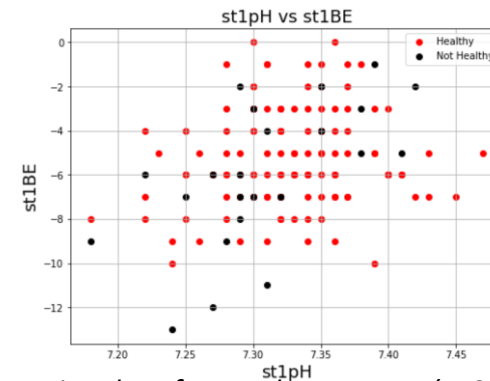


Fig: Plot of pH vs. base excess (KLS data)



Fig : Healthy vs. unhealthy confusion matrix

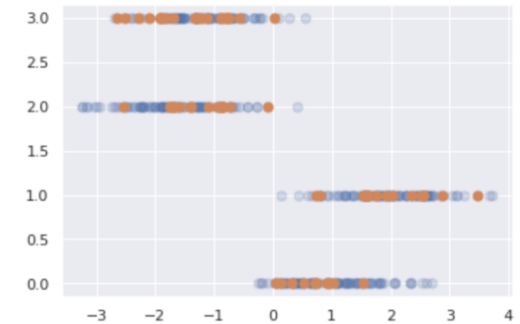


Fig: pH data after logistic regression

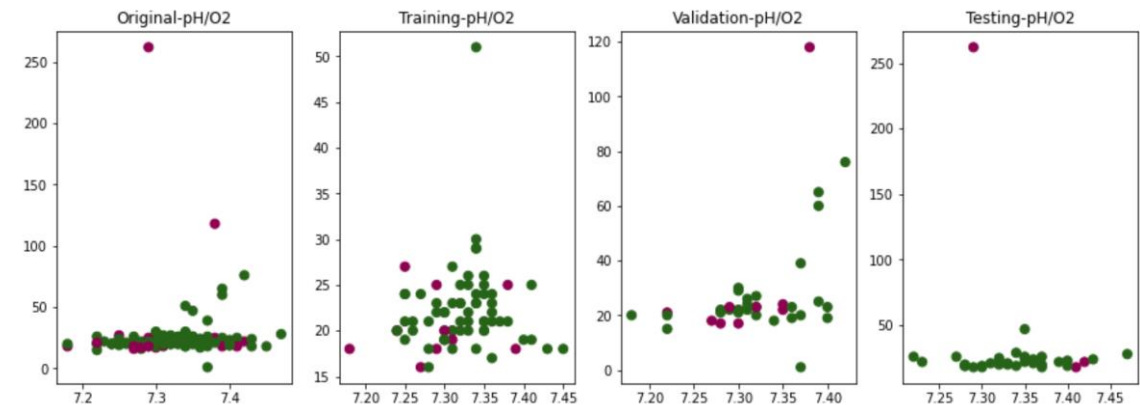


Fig : Illustrates how data is split up to train ML algorithm

# Next Steps

## Future Plans

- Refine individual sensors developed in lab
  - Glucose, pH
- Integrate sensors in prototype
  - Includes commercial oxygen, CO2 pending
  - KLS agreement to finalize analyte selection, ML to support
- Add Bluetooth capability to sensor
- Begin animal trials on rats

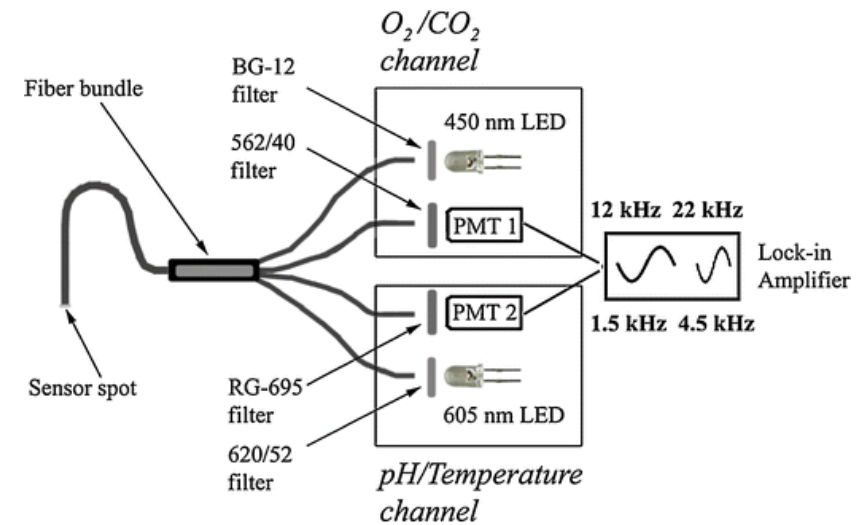


Fig : Illustrates ideal prototype integration, taken from Borisov SM et all [1]

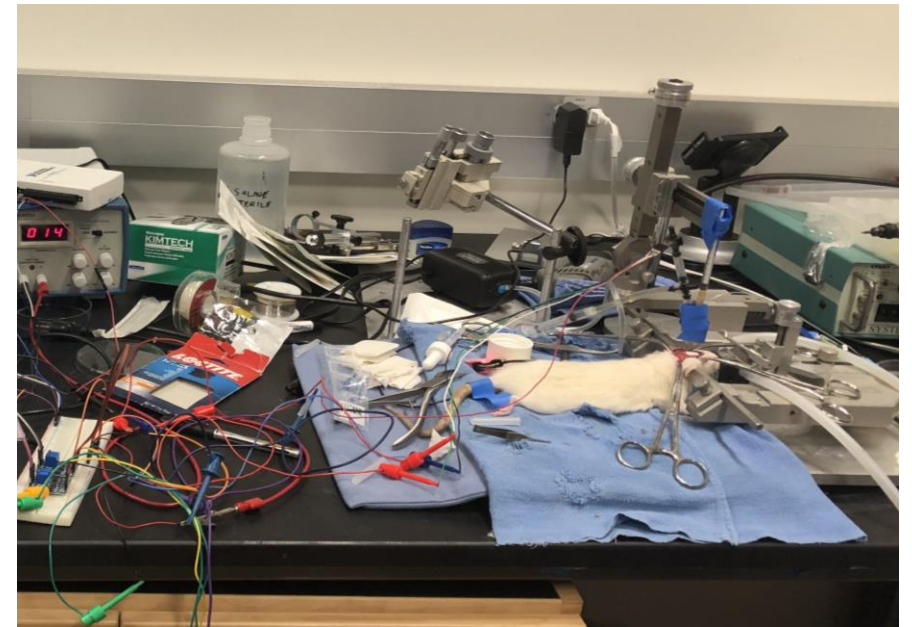


Fig : Rat surgeries conducted in BEST lab to test biomedical sensors

# Reflection

- Learned a lot about hardware sensor development
  - Applied textbook principles from Circuits 1&2 in the designing glucose PCB
- First thorough exposure to ML
  - Weekly Friday presentations from all REU students highlighted the versatility of ML
- Working with OB-GYNs from KLS gave insight to biomedical applications of my EE degree
- Valuable community of RET participants, Karl Ernsberger and Raquel Diaz
- Many thanks to Dr. Gulick, Dr. Liu, Ian Akamine, Arnav Bawa, Dr. Jaskie, Dr. Blain Christen, Dr. Spanias, & KLS mentors!



Fig: REU participants



Fig: RET participants

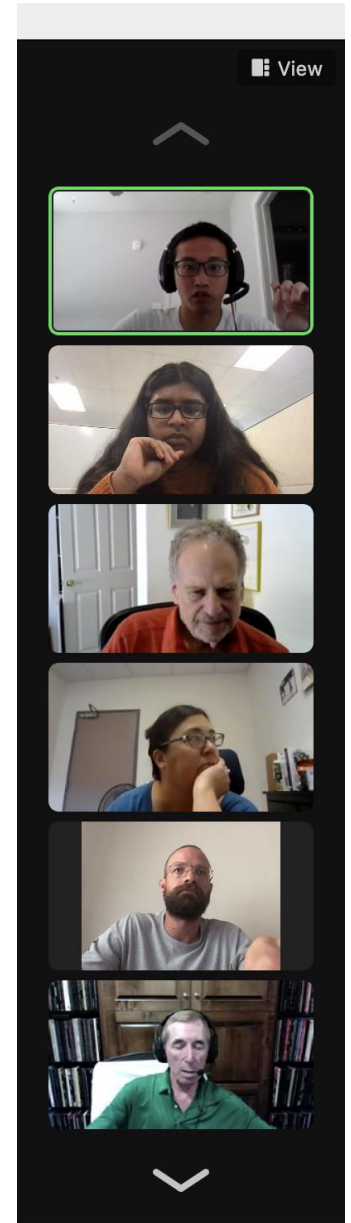


Fig: KLS team

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